Corrigendum: Geometry and Inverse Kinematic at the MP3R Mobile Systems

¹Relly Victoria Virgil Petrescu, ²Raffaella Aversa, ²Antonio Apicella, ³Samuel Kozaitis, ⁴Taher Abu-Lebdeh and ¹Florian Ion Tiberiu Petrescu

¹ARoTMM-IFToMM, Bucharest Polytechnic University, Bucharest, (CE) Romania

²Advanced Material Lab, Department of Architecture and Industrial Design, Second University of Naples, 81031 Aversa (CE) Italy

³Florida Institute of Technology, USA

⁴North Carolina A and T State University, USA

Correction to: Journal of Mechatronics and Robotics http://doi.org/10.3844/jmrsp.2017.58.65, published online 12 December 2017; updated 29 April 2019

The original version of this Article contained Mr. MirMilad Mirsayar as a Co-Author. Mr. Mirsayar has not contributed to the preparation and publication of this manuscript.

These errors have now been corrected in the HTML and PDF versions of the Article. http://doi.org/10.3844/jmrsp.2017.58.65.



© 2018 The Author(s). This open access article is distributed under a Creative Commons Attribution (CC-BY) 3.0 license.